drive.web
smarty-yf7

dw115 - Installation & Operation Manual

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⚠ Warning!

It is essential that you read and understand this entire manual, the entire Yaskawa F7 User Guide and the entire contents of the *savvy* software "Help" menu before proceeding with your installation and product configuration. For more information and to download product manuals and software, go to *www.driveweb.com*.

⚠ Warning!

Your use of *savvy* software, *drive.web* devices and drives may cause motors and machinery to power up with high voltages or start or operate in an unexpected, dangerous or lethal way. It is essential that you are completely familiar with *savvy* and all of the equipment and the system design you are working with before attempting to program or edit a program or connect to any live device.

⚠ Warning!

You are entirely responsible for the configuration or use of any *drive.web* product. By configuring or using these products you agree to indemnify and hold harmless Bardac Corporation, its' employees, directors, officers, distributors and resellers against the consequences of your configuration or use of the products.

dw115 smarty-yf7 Introduction

Take control of your **Yaskawa F7**, expand your interface and add computation power with this rugged, versatile, and easy to use, process and drives management system. Create large integrated systems where processing bandwidths are not affected by system size.
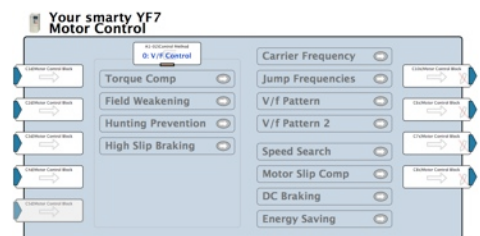
smarty-yf7 Features

- *drive.web* Distributed Process Control over **Ethernet**
- **Modbus TCP/IP over Ethernet** with option 04.
- **Internet accessible** configuration, monitoring & control.
- **"Drag 'n drop,"** easy connections with graphical documentation.
- Automated, on-line upgrades with *savvy* software.
- **System libraries** Basic, Process Control, Winders, Math & Encoder.
- **Function Blocks**; Extensive drive parameter control and monitoring. Arithmetic, logic, PID, comparator, filter, latch, timer, counter, ramps, winder diameter, taper tension, torque compensator, more.
- **I/O options;** Universal In, Analog Out, Digital I/O, Two Encoders, and Ethernet.
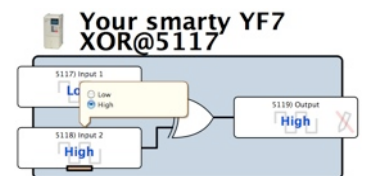
smarty-yf7 Available Options

smarty-yf7 models include *drive.web* over Ethernet, Distributed Process Control, comprehensive **Yaskawa F7** interface via 19.2 kbps, EIA485 serial connection, **Basic Control** Function Block Library with arithmetic, logic, PI, clamps, data switches and more. Please see Appendix A for a complete listing of function blocks by library and option.

03 I/O Package - UIP's (7), AOP's (2), DIO's(3), **10V Ref.** 10mA max.

Seven Universal Inputs multi-range analog, digital, differential

Two Analog Outputs 0 to 10V, 10mA max. 10 bit resolution

Three configurable Digital Inputs or Outputs. 24V, 50mA output.

04 ModbusTCP/IP. Ethernet, 10baseT enabled Modbus slave/server.

05 Process Control. Function Block Library 1 - Math, Logic, PID, Switches, Comparators, User data log, Profiler, Presets, Latch, Filters, Counters, Timers and more, see Appendix A.

06 Winder Control Function Block Library 2 - Diameter Calculator, Taper Tension, Torque Compensator.

07 and 08 Encoder 1 and 2 Inputs. Bi-directional with marker, EIA 422/485, 24V, 300kHz With encoder logic, position, speed functions.

09 Real time clock-battery backup, calendar, and event time-stamp.

**10 Advanced Math** Function Block Library 3 - Trig, Polynomials, Log, Exponent, more, see Appendix A.

11 Encoder Control Function Block Library 4 - Speed Lock, Registration, Position (Requires Option 07 and 08)

smarty-yf7 Options Important Notes:

Options 04, 05, 06, 10 and 11 are software options, easily field installed.

Option 08 includes an isolated serial port with green and yellow LEDs that indicate EIA485 data being received and transmitted.

Your use of *smarty* option **04** may cause motors and machinery to power up with high Voltages or start or operate in an unexpected, dangerous or lethal way. IT is essential that you are completely familiar with the ModbusTCP/IP protocol and all of the the equipment and the system design you are working with before attempting to use this option.
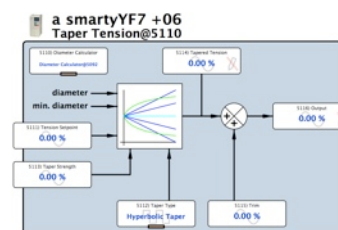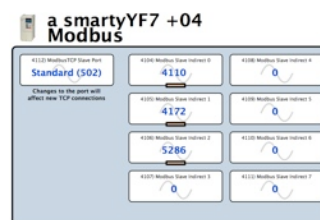
smarty-yf7 Winder Specials

Include options **05** and **06**, pre-installed generic winder **system configuration** and a wiring diagram drawing for fast commissioning of a wide range of winder applications.

1101 *smarty winder 1* Open Loop Constant Tension Center Winder.

1102 *smarty winder 2* Closed Loop Dancer Control Center Winder.

1103 *smarty winder 3* Closed Loop Loadcell Control Center Winder.

smarty-yf7 Physical Installation
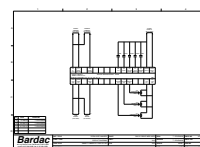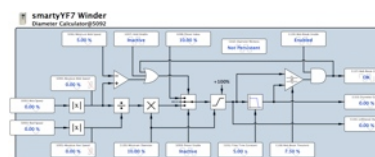
Mount on DIN rail in an electrical enclosure that provides the required environmental protection. You can mount with zero clearance on the side of the drive but provide at least 5" space if mounting directly above or below the drive.

smarty yf7 **Dimensions and Weight:** 2.3"w, 4.5"h, 4.7"d (59, 115, 120mm) 1.0 lb (0.45 Kg)

smarty yf7 **Power Requirements:** Regulated 24VDC ±15%, 50mA plus loads.

smarty is fitted with a 1A auto reset fuse

smarty yf7 **Storage and Operation Environment:** Temperature range; 0 to 50C. Humidity less than 95% non-condensing.

smarty yf7 **Ethernet Port** Standard RJ45 8P8C, 10BaseT, Link and Activity LED's

Set up Your *Yaskawa F7*, WARNING!

You must read and understand the entire Yaskawa F7 User Manual before proceeding! Dangerous, high voltages will exist that may cause **injury or death!** Only qualified personnel should proceed!

Check parameter *U1-14, Flash ID = 3020*. This is currently the only supported software.

You will need to connect the terminals, *S-* and *R-*, together for *EIA485-* or *A*. *S+* and *R+* connected together make the *EIA485+* or *B* connection. Connect *1G* directly to *C*.

Set the **baud rate** at parameter **H5-02 to 4** for 19.2 kbps.

Check the **Modbus Unit address, Parity and Delay times** are at default settings:

H5-01 = 1F = Address, decimal 31
H5-03 = 00 No Parity
H5-06 = 05 Minimum delay, 5ms

Based on your application, set *H5-04*, *Stopping Method* and *H5-05*, *Serial Fault Detect* to determine how the drive will respond to a serial connection loss.

Important Note: You must cycle the **YF7**'s power, waiting for the screen to blank before repowering, in order for the changes to take effect.

smarty-yf7 Ethernet Networking & Programming

It is important to have a basic understanding of Ethernet TCP/IP networks. Assigning an invalid or duplicate IP address will cause serious network malfunctions! *speedy485*s are all shipped with the IP address, 10.189.189.189. Consult your company's IT department for an appropriate, unique IP address.

Find useful networking information in the *Basic Network Administration* in the *savvy* user manual under the *Help* menu.

Set up Your Physical Ethernet Network - You Will Need:

A standard Category 5e cable (with 8P8C/RJ-45 connectors on both ends) for each *drive.web* device and your computer.

An Ethernet switch with sufficient ports to support all your *drive.web* devices and your computer.

Set up Your Computer - Get *savvy*

With free *drive.web savvy* software, easily program and monitor your *smarty-yf7*, perform data trending and create distributed control systems.

Download the latest version of *savvy* and view the *savvy* user manual. Go to *driveweb.com*, click on *Get savvy* or get *savvy* on the *Bardac* **Infodisk**.

Windows users will need to have **Java Runtime Environment** installed to run *savvy*. There is a link on the *Get savvy* page to download Java for free.
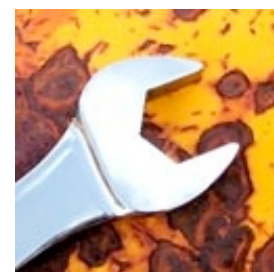
Get started with *savvy*

Before proceeding with your systems designs it is very important to familiarize yourself with *savvy*, the configuration software.

We strongly recommend that you read the introductory guides under the *Help* menu; *Getting Started with savvy*, *Getting Started with savvy-SFD*, and *savvy-SFD and the PL series drive*.

Use *Create Phantom* in the *Directory* menu to practice, explore all *drive.web* products and options and design and configure off-line. Design systems in Phantom devices and *Export Data* under the *Directory* menu for later use in live devices. *Import Data* into phantoms to work off-line.

We strongly recommend you attend our free on-line training seminars. Call us or email **training@driveweb.com** to register.

Under the *Directory* menu, click on *Discover All Local Devices*. If your *smarty-yf7* is powered up and physically connected to the same local network as your computer, an icon should appear on the screen.

If the icon at right appears with the red padlock and comms-fail indication, a network connection problem exists. Check connections, LEDs and that the *smarty* IP address is within your computer's subnet mask.

Warning! Changing a device IP address WILL disrupt its network connections! If a *smarty* is communicating with other devices or drives you must be prepared for system disruption and to remap connections in those devices when changing an IP address. In the *File* menu choose *Utility > Remap Export File* to remap a *dw-system* file with different IP address(es).

Under the *File* menu click *Set IP Addresses for System*. Identify your *smarty*'s serial number and enter an IP address within your computer's subnet mask. A **YF7** icon should appear.

The icon with question mark indicates no communication has been made. The clear icon indicates a good serial connection. The double arrow and yellow triangle instantly warns you if serial communication with the drive is interrupted.

If a red warning triangle is superimposed on the icon, your computer has lost Ethernet communication with your *smarty*. Check your Ethernet connections and that your *smarty* still has 24VDC power.

Right click on the icon and choose *Change Name* to name your *smarty.*

Click the **YF7** icon to view the first level, device overview screen. You can access the drive control and monitoring parameters, the Function Block Engine and if you have option **04**, a Modbus icon. Left click to view the next level.

Click on function blocks to view and adjust parameters.

Click on parameters to open the setter box unless they show a crossed-out pen meaning that they are read-only. You can adjust the parameter value with mouse or keys.

Right-click on parameters to get info, add to a dock, copy, start or end connections, rename, and rescale.

drive.web works with 16 bit words allowing raw decimal integer values **0 to 65535 or ±32767.** These raw values are limited and/or scaled depending on the parameter. This prevents illegal values and presents numbers in the most useful formats. Right-click to adjust scaling to fit your needs. Check scaling when making connections.
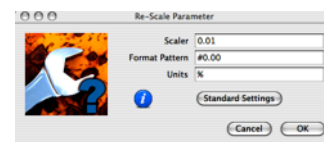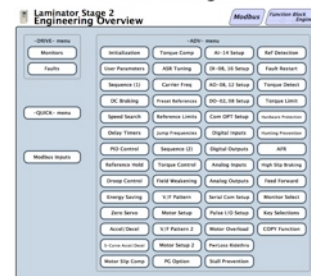
10.189.189.189

192.168.1.25

192.168.1.25

192.168.1.25

Laminator Stage 2

Upgrade *savvy* with Signal Flow Diagram Option - SFD

With *savvy-SFD*, build systems graphically while creating live drawings that are stored in your *speedy485*.

Set borders, drag and drop connections, zoom, pan, cross-reference and annotate multi-page drawings.

A separate function block and connection listing shows program execution order from top down. Change execution order by dragging function blocks up or down.

Select **Upgrade savvy** under the **Commerce** menu. Process a **Voucher** or credit card on-line any time. Contact us with the *savvy* ID shown in the **About drive.web savvy** window for an off-line upgrade **Coupon**.
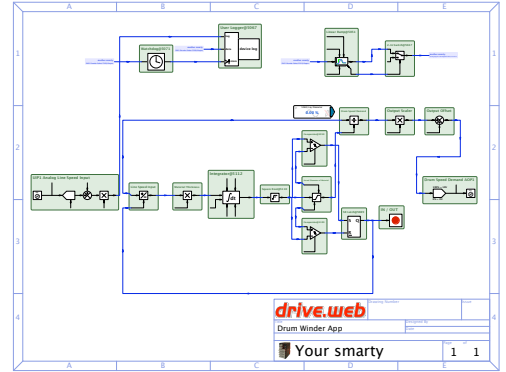
smarty-yf7 Terminals

24VDC power supply input

Serial port with option 08 is isolated. Includes LEDs, green, data received, and yellow, data sent.

10base T Ethernet port, RJ45 with LEDs. Green, link & yellow, activity for easy programming and networking.

Terminal Block A
Encoder 2 Input (Option 08)

Terminal Block B
Encoder 1 Input (Option 07)

Terminal block C
10V Ref., Analog Out & Digital Input/Outputs

Terminal Block D
Universal Input/Outputs, 0V Ref.

smarty-yf7 Option 03 AOP, DIO & UIP

Terminal	Function
C1	+10V Ref.
C2	AOUT1
C3	AOUT2
C4	0V
C5	DIO1
C6	DIO2
C7	DIO3
C8	0V

Terminal	Function
D1	UIP1
D2	UIP2
D3	UIP3
D4	UIP4
D5	UIP5
D6	UIP6
D7	UIP7
D8	0V

## Terminal Block C ~ 10V, Analog Outputs and Digital I/O

C1, 10V Reference. Supplies 10mA max current.

C2, C3, Two Analog Outputs. 0V to 10V, 10mA source,10 bit res. Input parameter 0% to 100% translates to 0V to 10V output.

C5, C6, C7, Three Digital I/O Terminals. Click on the, "Output Enable," parameter to change from input to output or connect to dynamically configure. Connect, 0 = Input and 1 = Output.

~ **Output Configuration; 24V with 50mA** max. source current is output to the terminal when the function block's input parameter is set to **High** or ≥ 1

~ **Input Configuration**: Input parameter is ignored and output parameter follows 24V logic at the terminal. High = 1 and Low = 0. Threshold is ~8V with 4V hysteresis. 12V logic may NOT function properly.
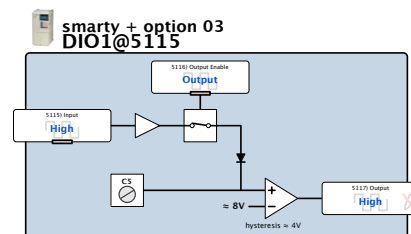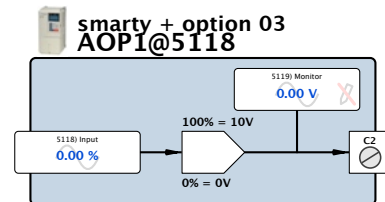
Terminal Block D ~ Universal Analog/Logic Inputs

**D1 - D7, Seven UIP's** 100KΩ input impedance, 12-bit resolution.

~ Monitor a terminal as an analog, logic, or differential input in separate function blocks.

~ Dynamically configure logic and analog ranges by connecting to the Range parameter.

~ Set the Differential Block Range to the maximum expected voltage difference between the two input terminals. The output is the percentage difference between the terminals over this range.
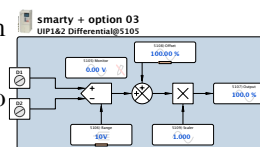
UIP Differential

Range	Input Ranges
0	100 mV
1	5 V
2	10 V
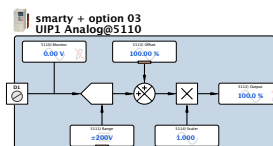
UIP Analog Block

Range	Analog Range
0	± 100 mV
1	± 5 V
2	± 10 V
3	± 100 V
4	± 200 V
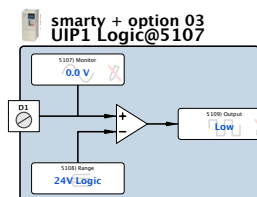
UIP Logic Block Digital Thesholds

Range	Turn-On	Turn-Off
5V	0.83V	2.5V
12V	2V	6V
24V	4V	12V

Option 04 ModbusTCP/IP Server

Conformance Class 0, Function Codes 03 &16.

Up to three simultaneous masters.

View the **Modbus Slave** function block by clicking on the **Modbus** icon in your **savvy** system configuration.

ModbusTCP Slave Port 502 is the standard specified in the protocol. You can change to match the Modbus master in the unusual case that it is non-standard.

Modbus Slave Indirect parameters are sequentially numbered so all or groups can be read or written with one command. Enter any parameter number in your function block engine in these parameters. Create more **Modbus Slave Indirect** blocks from the **Utility** function block list group.

~ You are not required to use the **Modbus Slave Indirect** blocks. Your ModbusRTU master can directly address any numbered parameter in your function block engine.

~ Right-click on parameters and **Get Info**. You cannot write or force parameters that cannot have incoming **drive.web** connections nor parameters with incoming **drive.web** connections indicated by a blue arrow at left side of the parameter block.
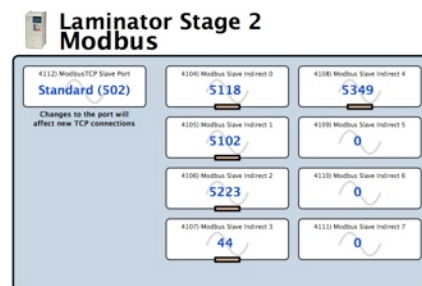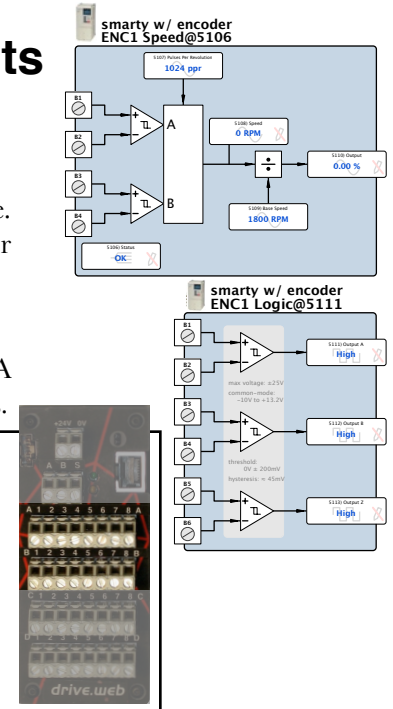
smarty Option 07 and 08, Encoder Inputs

- Encoder inputs are EIA422/EIA485 receivers, **24V, 300KHz max. freq.**

- Two function block types provide bidirectional speed and logic information.

- Notice that EIA422/485 signals should be complementing differential-type. The "+" line must swing negative with respect to the "-" line for proper operation. A single ended 0 to 24V logic signal may NOT register correctly.

- Option 08 requires option 07.

- Speed block includes a status parameter that indicates fault conditions on A and/or B. Use this parameter to verify your EIA422 signals and connections.

Encoder Terminals:

Enc.1 Opt. 07	Enc.2 Opt. 08	Description
B1	A1	Encoder A+
B2	A2	Encoder A-
B3	A3	Encoder B+
B4	A4	Encoder B-
B5	A5	Encoder Marker Z+
B6	A6	Encoder Marker Z-
B7	A7	+24VDC encoder power supply, 200mA max.
B8	A8	0V

smarty Option 11 Encoder Control F. B. Library 4

Option 11 requires option 07 and 08 and provides Position, Speed-lock and Registration function blocks.

Encoder Position Function Block

Set up this block for absolute position measurement:

1. Choose mechanical positions for 0 and 100%.

2. Enter number of encoder revolutions required to move from 0 to 100%

3. You may dynamically update your 0% position with a zero-position signal input connected to the, "Reset," parameter.

Encoder Speed Lock Function Block

Use this block to provide a numerical speed error signal.

Check *savvy* User Manual, Appendix A for detailed information on the following system implementations:

Create a Master Speed Follower, Speed Lock system:

Condition the error signal through a *PI* function block or similar and output a speed reference to a follower drive.

Create a Phase Lock system:

Condition the error signal through an *Integrator* and then through a *PI* function block or similar and output to drive.

Encoder Registration Function Block

Use this block to measure time or pulse delay between markers.

Choose whether the registration markers are signals on Digital I/O inputs 1 and 2, Encoder markers Z or combinations of DIO's and Z's.
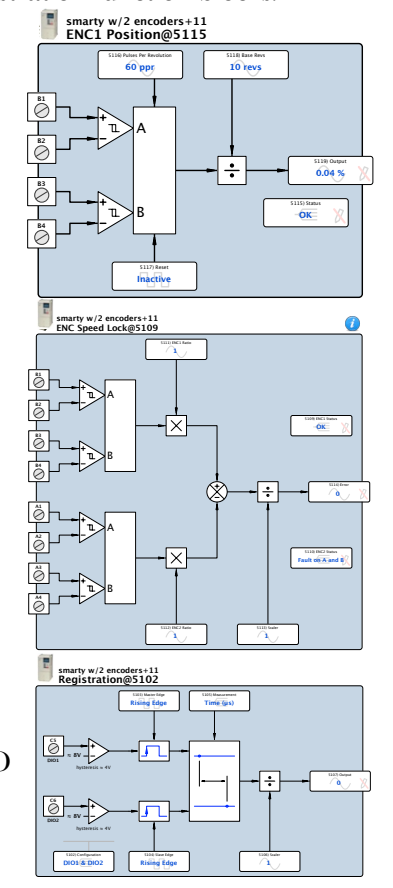
smarty Appendix A Function Blocks by Library and Option

Bold header indicates function block category. Precursor number is # of parameters inside each block.

Basic *smarty*

Arithmetic
3 Adder
3 Divider
3 Multiplier
3 Subtracter
Clamps
4 Clamp

Control
15 PI
Drive Helper
11 Optidrive Helper
Logic Gates
3 AND
2 NOT

3 OR
Switches
4 2-In Switch
4 2-Out Switch
Utility
1 Dev. Comms Monitor
1 Indicator

4 Parameter Block
6 Watchdog
1 Watchdog Driver

Process Control Library Option 05

Arithmetic
3 Differential Splitter
4 Multiplier-Divider
3 Sign And Value
3 Sign Changer
Clamps
5 Clamp with Monitor
4 Deadband
4 Skipband
Comparators
4 Comparator
5 Equality Comparator
3 Maximum
3 Minimum
6 Window Comparator
Control
6 Differentiator
8 Integrator

15 PI
20 PID
8 Profiler
Counters
17 Up/Down Counter
Drive Helper
11 Optidrive Helper
Filters
4 Low Pass Filter
5 Moving Average Filter
Latches
4 D Latch
5 D Latch with Reset
5 D Latch with Set
6 D Latch w/Set, Reset
3 SR Latch
4 T Latch

Logic
17 16-Bit Binary Encod.
17 16-Bit Binarty Decod.
5 4-Bit Binary Encoder
16 4-Bit Priority Encod.
3 Bitwise AND
2 Bitwise NOT
3 Bitwise OR
3 Bitwise Shift
3 Bitwise XOR
Logic Gates
3 NAND
3 NOR
3 XNOR
3 XOR
Ramps
7 Linear Ramp
11 MOP

17 S Ramp
Switches
18 16-In Switch
18 16-Out Switch
6 4-In Switch
6 4-Out Switch
10 8-In Switch
10 8-Out Switch
3 Track and Hold
Timers
5 Delay-Off Timer
5 Delay-On Timer
3 One Shot
5 Oscillator
8 Underlap
Utility
4 User Logger

Option 02, 04

Utility
4 Modbus Indirect

Option 03

I/O
2 AOP's
3 DIO's
5 UIP Differential
5 UIP Analog
3 UIP Logic

Option 06

Winder
18 Diameter Calculator
7 Taper Tension
30 Torque Compensator

Options 07,08

I/O
3 ENC Logic
5 ENC Speed

Option 10

Math
2 ArcCosine
2 ArcSine
2 ArcTangent
2 Cosine
2 Cube
2 Cube Root
2 Exponential
2 Logarithm
2 Reciprocal
2 Sine
2 Square
2 Square Root
2 Tangent

Option 11

I/O
5 ENC Position
6 ENC Speed Lock
7 Registration

Option 12

ModbusRTU Master
7 Comms Port
48 EurothermERCFW09
6 Holding Reg. INT16
6 Holding Reg. UINT16
54 Optidrive Plus
54 Optidrive VTC
48 WEG CFW09

Appendix B *drive.web* Product Line Overview

smarty Full featured controller simultaneously manages many varied process components and drives.

speedy sp and *speedy485* Processing power, tailored for your drive or generic, Ethernet, EIA485

savvy **Signal Flow Diagram Option** Easily implement your systems designs. **"Drag n' Drop,"** connections with complete, graphical documentation created in one step and stored in your device.

drive.web **Training Courses**-an essential component in your *drive.web* system. On-line and factory courses are available at all technical levels. Sign up to get the most out of your *drive.web* technologies.

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